

Theory of Matrices

Lecture 1,
1/21/09

Syllabus - HW - can work together, come to office for help, but must write up own work.

Show work - answers often in text.

Late HW - penalty for unexcused.

Reading - read text and assigned problems (most proofs are in "solved problems.")

Theory/Proofs - very important part of course.

Expected to read, listen to, write proofs:

See "Guidelines for Writing Proofs," and follow.

Review - see handout on background material.

Vector Spaces [See §4.1 for notation]

In basic linear algebra we primarily studied the vector space $\mathbb{R}^n = \{(a_1, a_2, \dots, a_n) \mid a_i \in \mathbb{R}\}$ with vector addition and scalar multiplication defined componentwise.

We generalize this, using as axioms the basic properties we know about \mathbb{R}^n . [See Theorem 1.1, p 4]

In general, Scalars are taken from an arbitrary field K . A field is an algebraic structure similar to \mathbb{R} :

a set with addition and multiplication defined satisfying associative, commutative, and distributive laws, containing additive and multiplicative identities $(0, 1)$ and additive inverses for all elements, multiplicative inverses for nonzero elements.

Examples are \mathbb{Q} (rationals), \mathbb{R} (reals), \mathbb{C} (complex numbers)

Most theorems and definitions will be stated for an arbitrary field K , but it is usually no harm to substitute \mathbb{R} for K (or at least think of K as \mathbb{R}).