

[Notes on Proof, continued]

For statement (2), observe that  $m_T(t) = 0$  and the multiplicity of  $t - \lambda$  as a factor of  $m_T(t)$  is the smallest power needed to "kill" all of the  $\lambda$ -blocks. Since  $(J_\lambda - \lambda I)^m = 0$  but  $(J_\lambda - \lambda I)^{m-1} \neq 0$  for a  $\lambda$ -block  $J_\lambda$  of size  $m$ , this power is the size of the largest  $\lambda$ -block.

For statement (3), if  $A$  is the Jordan Form of  $T$ , then  $A - \lambda I$  has one zero column for each block (the first column in the block) and all other columns are linearly independent. Hence the number of blocks is equal to the number of zero columns of  $A - \lambda I$ , which is equal to  $\dim \mathcal{N}(A - \lambda I) = \dim E_\lambda$ .

For statement (4), see text, Problems 10.16, 10.18.  $\square$

Remarks:

- ① In statement (4),  $(T - \lambda I)^0$  should be interpreted as the identity operator, so  $\text{nullity}(T - \lambda I)^0 = 0$ ,  $\text{rank}(T - \lambda I)^0 = \dim V$ .
- ② We have seen that  $\text{ker}(T - \lambda_i I)^{l_i} = \text{ker}(T - \lambda_i I)^{l_i+1} = \dots$ . Hence finding  $\dim \text{ker}(T - \lambda_i I)^k$  for  $k = 1, 2, \dots, l_i$  and using (4) is always sufficient to find the Jordan Form. This, however, may be a lot of work and is necessary only if the Jordan Form is not uniquely determined by (1) - (3).

In fact, we have [exercises]:

- If every eigenvalue of  $T$  has algebraic multiplicity at most 3, then  $\Delta_T(t)$ ,  $m_T(t)$  completely determine Jordan Form.
- If every eigenvalue of  $T$  has algebraic multiplicity at most 6, then  $\Delta_T(t)$ ,  $m_T(t)$ , and  $\dim E_\lambda$  for each  $\lambda$  determine the Jordan Form.

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