

EXAMPLES

(1) The "standard" inner product on  $\mathbb{R}^n$  generalizes the dot product on  $\mathbb{R}^2$ ,  $\mathbb{R}^3$ . For  $\bar{u} = (a_1, \dots, a_n)$ ,  $\bar{v} = (b_1, \dots, b_n)$ , we define

$$\langle \bar{u}, \bar{v} \rangle = a_1 b_1 + a_2 b_2 + \dots + a_n b_n \quad (= \bar{u} \cdot \bar{v})$$

[Exercise: Verify I<sub>1</sub>, I<sub>2</sub>, I<sub>3</sub>.]

Note: Unless otherwise stated, the standard inner product will be used when discussing  $\mathbb{R}^n$ . This is not the only inner product on  $\mathbb{R}^n$ , however. For example:

(2) Let  $V = \mathbb{R}^2$ . We define another inner product as follows:

For  $\bar{u} = (x_1, x_2)$  and  $\bar{v} = (y_1, y_2)$  in  $\mathbb{R}^2$ , define

$$\langle \bar{u}, \bar{v} \rangle = x_1 y_1 - 2x_1 y_2 - 2x_2 y_1 + 5x_2 y_2.$$

That is, this is an inner product can be verified easily. The verification of I<sub>3</sub> is a little tricky:

If  $\bar{u} = (x_1, x_2)$  then

$$\begin{aligned} \langle \bar{u}, \bar{u} \rangle &= x_1 x_1 - 2x_1 x_2 - 2x_2 x_1 + 5x_2 x_2 = x_1^2 - 4x_1 x_2 + 5x_2^2 \\ &\stackrel{\Delta}{=} x_1^2 - 4x_1 x_2 + 4x_2^2 + x_2^2 = (x_1 - 2x_2)^2 + x_2^2 \geq 0. \end{aligned}$$

(here's the tricky part) Hence  $\langle \bar{u}, \bar{u} \rangle \geq 0$ .

Moreover,  $\langle \bar{u}, \bar{u} \rangle = (x_1 - 2x_2)^2 + x_2^2 = 0$  if and only if

$x_1 - 2x_2 = 0$  and  $x_2 = 0$ , hence also  $x_1 = 0$ . So  $\langle \bar{u}, \bar{u} \rangle = 0 \Leftrightarrow \bar{u} = \bar{0}$ .

(The verification of I<sub>1</sub>, I<sub>2</sub> are exercises.)

Sample Calculation:

$$\begin{aligned} \langle (1, 2), (3, -1) \rangle &= (1)(3) - 2(1)(-1) - 2(2)(3) + 5(2)(-1) \\ &= 3 + 2 - 12 - 10 = -17. \end{aligned}$$

(3) Let  $V = P_n(t)$ . For  $f(t) = a_0 + a_1 t + \dots + a_n t^n$ ,  $g(t) = b_0 + b_1 t + \dots + b_n t^n$ , define  $\langle f(t), g(t) \rangle = a_0 b_0 + a_1 b_1 + \dots + a_n b_n$ .

Observe that relative to the basis  $B = \{1, t, t^2, \dots, t^n\}$ , we have

$[f(t)]_B = (a_0, a_1, \dots, a_n)$ ,  $[g(t)]_B = (b_0, b_1, \dots, b_n)$  and  $\langle f(t), g(t) \rangle = [f(t)]_B^T [g(t)]_B$ . We generalize this in the next example.