

## A COMPARISON OF THE SUCCESSIVE OVERRELAXATION METHOD AND SEMI-ITERATIVE METHODS USING CHEBYSHEV POLYNOMIALS\*

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1. Introduction. It is the main purpose of this paper to compare the mean rates of convergence of two well-known schemes for solving self-adjoint partial difference equations of elliptic type: the Young-Frankel [6, 1] successive overrelaxation method, and the semi-iterative Chebyshev polynomial method as described by Lanczos [2, p. 42], Stiefel [3], and others. More generally, the analysis is applicable to any matrix equation of the form

$$(1) \quad Au = k,$$

provided the matrix  $A = \| a_{i,j} \|$  is symmetric and positive definite, and, in the sense of Young [6, p. 93], satisfies property (A).

For semi-iterative methods, one considers iterates  $u_i$ , where

$$(2) \quad u_{i+1} = Mu_i + k \quad (i = 0, 1, 2, \dots),$$

$M$  being a specific matrix. Then, one forms from the sequence of vectors  $u_j$  a new sequence of vectors

$$(3) \quad t_n = \sum_{j=0}^n v_j(n) u_j \quad (n = 0, 1, 2, \dots),$$

the constants  $v_j(n)$  being real numbers. Such a procedure is called a semi-iterative method with respect to the matrix  $M$ .

While it is known [8, p. 293] that the successive overrelaxation method converges at least twice as fast as any semi-iterative method with respect to the Jacobi method, we shall give a different proof of this result, which generalizes to semi-iterative methods with respect to the Gauss-Seidel method. For the Gauss-Seidel method, the result is that the successive overrelaxation method converges at least as fast as any semi-iterative method with respect to the Gauss-Seidel method.

When solution by high-speed computing machines is involved, it should be noted that the successive overrelaxation method has the further advantage of requiring no auxiliary storage of extra iterates  $u_m$ , whereas semi-iterative methods require that a few iterates  $u_m$  be stored, along with suitable coefficients.

In a final section, an analogous discussion is given for semi-iterative

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methods applied to matrices whose (complex) eigenvalues are known to be confined to a *circle* in the complex plane. The result is that the best semi-iterative method with respect to the successive overrelaxation method, assuming only that all eigenvalues  $\lambda$  of the successive overrelaxation method satisfy  $|\lambda| \leq \rho < 1$ , is simply the basic method repeated  $n$  times, where  $n$  is the order of the semi-iterative method.

2. Description of methods. Equation (1) is rewritten in the form

$$(4) \quad u = Bu + f$$

where the  $N \times N$  matrix  $B = \|b_{i,j}\|$  and the vector  $f$  are given by<sup>1</sup>

$$(5) \quad b_{i,j} = \begin{cases} -a_{i,j}/a_{i,i}, & i \neq j \\ 0, & i = j \end{cases}, \quad f_i = k_i/a_{i,i},$$

for  $i = 1, 2, \dots, N$ . For the successive overrelaxation method, one forms the sequence of vectors defined by

$$(6) \quad u_i^{(m+1)} = \omega \left\{ \sum_{j=1}^{i-1} b_{i,j} u_j^{(m+1)} + \sum_{j=i+1}^N b_{i,j} u_j^{(m)} + f_i \right\} + (1 - \omega) u_i^{(m)}$$

where the "overrelaxation factor"  $\omega$  is a parameter which is fixed throughout the course of iteration. The equation above may be written symbolically as

$$(7) \quad u_{m+1} = L_{\sigma,\omega}[u_m] + g,$$

where  $g$  is a fixed vector, and  $L_{\sigma,\omega}$  denotes a linear operator.

Let  $u_0$  be a "trial solution" of (1), and let the sequences of vectors  $u_j$  and  $t_n$  be defined, respectively, by (2) and (3). If  $u_0$  is the unique solution of (1), then each  $t_n$  is also a solution of (1) if and only if<sup>2</sup>

$$(8) \quad \sum_{j=0}^n v_j(n) = 1 \quad (n = 0, 1, 2, \dots).$$

If  $v$  denotes the unique solution of (1), and the  $n$ th error vector  $t_n - v$  is denoted by  $\epsilon_n^*$ , then

$$(9) \quad \epsilon_n^* = p_n(\mathbf{M})\epsilon_0, \quad p_n(x) \equiv \sum_{j=0}^n v_j(n)x^j,$$

and  $\epsilon_0 = u_0 - v$  is the error vector associated with the trial solution  $u_0$ . As

<sup>1</sup> Since  $A$  is symmetric and positive definite, (1) has a unique solution, and  $a_{i,i} > 0$  for all  $i$ .

<sup>2</sup> For polynomials similarly normalized, see [2, p. 41], and [3, p. 63].

## OVERRELAXATION AND SEMI-ITERATIVE METHODS

a consequence of (8), we shall henceforth assume  $p_n(1) = 1$ . For comparison, we note that in the successive overrelaxation method

$$(10) \quad \epsilon_n = L_{\sigma, \omega}^n[\epsilon_0],$$

which corresponds to the choice  $p_n(x) = x^n$ , and  $M = L_{\sigma, \omega}$ .

If the matrix  $M$  has real eigenvalues  $\lambda_k$ , and the interval  $a \leq x \leq b$  is the smallest interval containing the  $\lambda_k$ 's, we define

$$(11) \quad \begin{aligned} \mu[p_n(M)] &= \max_{a \leq x \leq b} \{ |p_n(x)|^{1/n} \}, \\ R[p_n(M)] &= -\log \mu[p_n(M)]. \end{aligned}$$

The quantities  $\mu[p_n(M)]$  and  $R[p_n(M)]$  are respectively the *average spectral norm* and the *average rate of convergence*<sup>3</sup> at the  $n^{\text{th}}$  step of the semi-iterative method with respect to the matrix  $M$ . For  $p_n(x) = x^n$ , we see that  $\mu[p_n(M)]$  and  $R[p_n(M)]$  are independent of  $n$ , and are, for matrices  $M$  with real eigenvalues, respectively the usual definition of the spectral norm  $\bar{\mu}$  and rate of convergence  $R$  of  $M$  [6, p. 96].

3. Basis of Comparisons. In this section, we shall compare the rate of convergence of the successive overrelaxation method with that of the semi-iterative method with respect to the Jacobi method. We choose the matrix  $M$  of (2) to be the matrix  $B$  defined by (5). Under our initial assumptions,  $A$  is symmetric and positive definite, and satisfies property (A). For this case, it is known [6] that all the eigenvalues  $\lambda$  of  $B$  are real, and lie in the symmetric interval  $-\bar{\mu} \leq \lambda \leq +\bar{\mu} < 1$ , where  $\bar{\mu}$  is the spectral norm of  $B$ . Without loss of generality, we may assume that  $A$  is consistently ordered [6, p. 93]. The best choice [6] of  $\omega$  is given by

$$(12) \quad \omega_b = 1 + \left[ \frac{\bar{\mu}}{1 + [1 - \bar{\mu}^2]^{\frac{1}{2}}} \right]^2,$$

and

$$(13) \quad R[L_{\sigma, \omega_b}] = -\log(\omega_b - 1).$$

To select the best semi-iterative method with respect to the matrix  $B$ , we choose the polynomial  $p_n(x)$  such that

$$(14) \quad \max_{-\bar{\mu} \leq x \leq \bar{\mu}} |p_n(x)|$$

<sup>3</sup> Specifically, if the largest degree of the elementary divisors [5, Ch. III] of the matrix  $p_n(M)$ , for  $n$  fixed, is unity, then the reciprocal of  $R[p_n(M)]$  is an estimate of the least positive integer  $k$  for which

$$\| (p_n(M))^k \epsilon_0 \| \leq e^{-n} \| \epsilon_0 \|,$$

where  $\| x \|$  refers to the Euclidean norm of the vector  $x$ .

is smallest. It is well-known that the solution of this problem is in Chebyshev polynomials, and we have explicitly

$$(15) \quad p_n(x) = \frac{T_n(x/\bar{\mu})}{T_n(1/\bar{\mu})},$$

where  $T_n(x) = \cos [n \cos^{-1} x]$  is the Chebyshev polynomial of degree  $n$ . We shall call this particular method the Chebyshev semi-iterative method with respect to the Jacobi method. By definition, we have

$$\max_{-\bar{\mu} \leq x \leq \bar{\mu}} |p_n(x)| = \frac{\max_{-1 \leq x \leq 1} |T_n(x)|}{|T_n(1/\bar{\mu})|} = \frac{1}{T_n(1/\bar{\mu})},$$

since  $T_n(\alpha) > 1$  for  $\alpha > 1$ . Forming the ratio of the average rates of convergence of the successive overrelaxation method and this Chebyshev semi-iterative method, we have

$$R[L_{\sigma, \omega_b}]/R[p_n(B)] = \left[ \frac{2 \log [1 + (1 - \bar{\mu}^2)^{1/2}]}{\bar{\mu}} \right] / \left( \frac{\log T_n(1/\bar{\mu})}{n} \right).$$

Since, for  $\alpha > 1$ ,  $\log T_n(\alpha)/n$  increases monotonically to  $\cosh^{-1}(\alpha)$ , and since  $\cosh^{-1}(\alpha) = \log(\alpha + \sqrt{\alpha^2 - 1})$  for  $\alpha > 1$ , we have, replacing  $\alpha$  by  $1/\bar{\mu}$ ,  $R[L_{\sigma, \omega_b}]/R[p_n(B)] \geq 2$ . This proves in a different manner the following theorem of Young [8, p. 293].

**THEOREM 1.** *The successive overrelaxation method with the optimum overrelaxation factor converges at least twice as fast as the Chebyshev semi-iterative method with respect to the Jacobi method, and therefore at least twice as fast as any semi-iterative method with respect to the Jacobi method. Furthermore, as the number of iterations tends to infinity, the successive overrelaxation method becomes exactly twice as fast as this Chebyshev semi-iterative method.*

We finally remark that for values of  $\omega$  near the optimum  $\omega_b$ , the successive overrelaxation method still has a faster rate of convergence than the Chebyshev semi-iterative method with respect to the Jacobi method, and therefore a faster rate of convergence than any semi-iterative method with respect to the Jacobi method.

4. Extension to polynomials<sup>4</sup> in  $L_{\sigma, 1}$ . In this section, we merely replace the Jacobi matrix  $B$  in the previous section by the Gauss-Seidel or Liebmann operator  $L_{\sigma, 1}$  [1, 6]. Assuming  $A$  to be consistently ordered, it is then known [6, p. 100] that the eigenvalues  $\lambda_k$  of  $L_{\sigma, 1}$  satisfy  $0 \leq \lambda_k \leq \bar{\mu}^2 < 1$ , where  $\bar{\mu}$  is the spectral norm of the matrix  $B$ . As before, the polynomial  $p_n(x)$  of degree  $n$ , normalized so that  $p_n(1) = 1$ , which has the property

<sup>4</sup> See also [4, Chapter VI].

OVERRELAXATION AND SEMI-ITERATIVE METHODS

that  $\max_{0 \leq x \leq \bar{\mu}^2} |p_n(x)|$  is smaller than all other such normalized polynomials, will be

$$(16) \quad p_n(x) = T_n\left(\frac{2x}{\bar{\mu}^2} - 1\right) / T_n\left(\frac{2}{\bar{\mu}^2} - 1\right).$$

The semi-iterative method based on these polynomials will be called the *Chebyshev semi-iterative method with respect to the operator  $L_{\sigma,1}$* . The average rate of convergence of this iterative scheme at the  $n$ th step is

$$(17) \quad R[p_n(L_{\sigma,1})] = \log T_n\left(\frac{2}{\bar{\mu}^2} - 1\right) / n.$$

If we form the ratio of  $R[L_{\sigma,\omega_b}]$  to  $R[p_n(L_{\sigma,1})]$ , then using the monotone property of  $\log T_n(\alpha)/n$  and the previously used identity for  $\cosh^{-1}(\alpha)$  for  $\alpha > 1$ , we obtain

$$(18) \quad \begin{aligned} & R[L_{\sigma,\omega_b}] / R[p_n(L_{\sigma,1})] \\ & \geq 2 \log \left( \frac{1}{\bar{\mu}} + \left( \frac{1}{\bar{\mu}^2} - 1 \right)^{\frac{1}{2}} \right) / \log \left( \frac{2}{\bar{\mu}^2} - 1 + \left( \left( \frac{2}{\bar{\mu}^2} - 1 \right)^2 - 1 \right)^{\frac{1}{2}} \right). \end{aligned}$$

But the right hand side of the inequality above reduces identically to unity for  $\bar{\mu} < 1$ . This proves

**THEOREM 2.** *The successive overrelaxation method with the optimum overrelaxation factor converges at least as fast as the Chebyshev semi-iterative method with respect to the operator  $L_{\sigma,1}$ , and therefore at least as fast as any semi-iterative method with respect to the operator  $L_{\sigma,1}$ . Furthermore, as the number of iterations tends to infinity, the successive overrelaxation method becomes exactly as fast as the Chebyshev semi-iterative method with respect to the operator  $L_{\sigma,1}$ .*

**5. Extensions to polynomials in the operator  $L_{\sigma,\omega}$**  - If we have, as before, that the eigenvalues of  $B$  are real and lie in  $-\bar{\mu} \leq x \leq \bar{\mu}$ , then we can formulate the problem of finding the best polynomial of degree  $n$ , normalized so that  $p_n(1) = 1$ , having the smallest absolute value on the interval  $-\bar{\mu} \leq x \leq \bar{\mu}$ , and we are naturally led to Chebyshev polynomials. With these polynomials, we then defined the Chebyshev semi-iterative method with respect to the matrix  $B$ , which was, in some sense, the optimum semi-iterative method with respect to the matrix  $B$ . The same is true if we consider, rather than the matrix  $B$ , the linear operator  $L_{\sigma,1}$  whose eigenvalues  $\lambda_k$  are also real and satisfy  $0 \leq \lambda_k \leq \bar{\mu}^2$ , and optimize the selection of a sequence of normalized polynomials whose absolute value on the interval  $0 \leq x \leq \bar{\mu}^2$  is smallest. The resulting semi-iterative method defined by this sequence of polynomials was called the Chebyshev semi-iterative method with respect to the operator  $L_{\sigma,1}$ . As we pass to the case where

$1 < \omega < 2$ , the operator  $L_{\sigma, \omega}$  does not have all real eigenvalues [6, p. 101], and the selection of a sequence of normalized polynomials to define a semi-iterative method with respect to the operator  $L_{\sigma, \omega}$  is not immediate. As before, we have

$$(19) \quad \epsilon_n^* = \sum_{j=0}^n \nu_j(n) L_{\sigma, \omega}^j \epsilon_0 = p_n(L_{\sigma, \omega}) \epsilon_0,$$

where  $p_n(1) = 1$ . We now assume that the eigenvalues  $\lambda_k$  of  $L_{\sigma, \omega}$  satisfy  $|\lambda_k| \leq \rho < 1$ . If  $g_n(z)$  is any complex polynomial of degree  $n$ , let  $M_{g_n}(r)$  denote the maximum modulus function of  $g_n(z)$ , i.e.,

$$M_{g_n}(r) = \max_{|z| \leq r} |g_n(z)|.$$

Completely analogous to the previous sections, let  $S_n$  be the set of all polynomials  $g_n(z)$  of degree  $n$  for which  $g_n(1) = 1$ , and consider

$$\min_{g_n \in S} \{M_{g_n}(r)\}.$$

The following theorem, due to E. H. Zarantonello<sup>5</sup>, seems to be of interest by itself.

**THEOREM 3.** For all  $r$  such that  $0 \leq r \leq 1$ ,  $\min_{g_n \in S} \{M_{g_n}(r)\} = r^n$  for all positive integers  $n$ .

**PROOF.** As is well known, we have

$$M_{g_n}(r) = \lim_{p \rightarrow \infty} \left\{ \int_0^{2\pi} |g_n(re^{i\theta})|^{2p} d\theta \right\}^{1/2p}.$$

Clearly, we have for any positive integer  $p$ ,

$$\min_{g_n \in S_n} \left\{ \int_0^{2\pi} |g_n(re^{i\theta})|^{2p} d\theta \right\}^{1/2p} \geq \min_{Q \in S_{np}} \left[ \left( \int_0^{2\pi} |Q(re^{i\theta})|^2 d\theta \right)^{\frac{1}{2}} \right]^{1/p}$$

since if  $g_n \in S_n$ , then

$$Q(z) = [g_n(z)]^p \in S_{np}.$$

If

$$Q(z) = \sum_{k=0}^{np} a_k z^k,$$

then

$$\left( \int_0^{2\pi} |Q(re^{i\theta})|^2 d\theta \right)^{\frac{1}{2}} = \sqrt{2\pi} \left( \sum_{k=0}^{np} |a_k|^2 r^{2k} \right)^{\frac{1}{2}}.$$

<sup>5</sup> Personal communication.

OVERRELAXATION AND SEMI-ITERATIVE METHODS

But

$$\sqrt{2\pi} \left( \sum_{k=0}^{np} |a_k|^2 r^{2k} \right)^{\frac{1}{2}} \geq \sqrt{2\pi} r^{np} \left( \sum_{k=0}^{np} |a_k|^2 \right)^{\frac{1}{2}}$$

since  $0 \leq r \leq 1$ . Since  $Q \in S_{np}$ , then  $\sum_{k=0}^{np} a_k = 1$ . Therefore, using Schwarz' inequality, we have

$$1 = \left| \sum_{k=0}^{np} a_k \right| \leq \sum_{k=0}^{np} |a_k| \leq (np + 1)^{\frac{1}{2}} \left( \sum_{k=0}^{np} |a_k|^2 \right)^{\frac{1}{2}},$$

and

$$\left\{ \int_0^{2\pi} |Q(re^{i\theta})|^2 d\theta \right\}^{\frac{1}{2}} \geq \sqrt{2\pi} r^{np} \left( \sum_{k=0}^{np} |a_k|^2 \right)^{\frac{1}{2}} \geq \left( \frac{2}{np + 1} \right)^{\frac{1}{2}} r^{np}.$$

Thus,

$$\min_{Q \in S_{np}} \left[ \left( \int_0^{2\pi} |Q(re^{i\theta})|^2 d\theta \right)^{\frac{1}{2}} \right]^{1/p} \geq r^n \left( \frac{2}{np + 1} \right)^{1/2p}.$$

Letting  $p \rightarrow \infty$ , we have

$$\min_{Q_n \in S_n} M_{Q_n}(r) \geq r^n.$$

Since  $z^n \in S_n$ , and  $M_{z^n}(r) = r^n$ , then

$$\min_{Q_n \in S_n} M_{Q_n}(r) = r^n \quad \text{for all } 0 \leq r \leq 1,$$

for all positive integers  $n$ .

In view of this theorem, we have

**THEOREM 4.** *The best semi-iterative method with respect to the successive overrelaxation method,  $\omega > 1$ , which can be obtained, assuming only that eigenvalues  $\lambda_k$  of the successive overrelaxation method satisfy  $|\lambda| \leq \rho < 1$ , is simply the basic method repeated  $n$  times, where  $n$  is the order of the semi-iterative method.*

We remark that, for  $\omega > 1$ , the error vector associated with the best semi-iterative method with respect to  $L_{\sigma, \omega}$  satisfies

$$(20) \quad \epsilon_n^* = L_{\sigma, \omega}^n \epsilon_0 = \epsilon_n.$$

This particularly simple form of a semi-iterative method with respect to  $L_{\sigma, \omega}$  incidentally has been used repeatedly to solve multigroup diffusion problems in two or more (space) dimensions [9, 10]. Apparently, the choice for the iteration method is not related to the theorem above, but rather to the inherent simplicity of the iteration method of (20).

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